### Title of the Invention

## METHOD OF REDUCING UNNECESSARY BARRIER INSTRUCTIONS

#### Inventors

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# METHOD OF REDUCING UNNECESSARY BARRIER INSTRUCTIONS Field of the Invention

The present invention generally relates to a method of reducing unnecessary barrier instructions and, more particularly, to a method of reducing unnecessary barrier instructions affecting the execution performance of parallel processing of an object program in a multiprocessor system.

## Background of the Invention

A general barrier instruction issuing condition in a multiprocessor system occurs when a dependency between a certain data reference and a following data reference or the dependency relationship is unclear. If the presence or absence of this data dependency cannot be determined except at the time of instruction execution, or the dependency analysis of a compiler is disabled, barrier instructions are output for execution in the parallel processing object program.

Conventional methods for reducing unnecessary barrier instructions are known. In one example, a barrier instruction reduction directive statement for a compiler is inserted with a user directive statement or a data dependency cancellation directive statement is inserted in the source program.

FIG. 3 shows an example of a source program in which a directive statement for reducing unnecessary barrier instructions is inserted. This source program is written in an implementation of FORTRAN that is extended for paralleling

capability. A description of an example of the source program is as follows.

The source program shown in the example of FIG. 3 includes a DO loop 31 for iterative execution of processing by substituting the values i = 1 to n sequentially into an array indicated by a(i). If an overlap between the reference range of array "a" in the DO loop 31 and the reference range of a following array 33 cannot be determined at the time of compilation and therefore can be determined only at the time of instruction execution, a barrier instruction reducing directive statement 32 for the compiler needs to be inserted by the user with a user directive statement. It should be noted that this directive statement 32 may be a data dependency cancellation directive statement. It should also be noted that "POPOPTION" is a directive statement indicating that the user provides a directive for paralleling a portion of the program that cannot be automatically put in parallel processing form by a parallel processing capability implemented by a FORTRAN processing system.

## Summary of the Invention

Generally, the execution of a barrier instruction causes overhead. The execution performance of the processing system is decreased by the amount of execution of unnecessary barrier instructions. The above-mentioned prior art is intended to reduce the number of unnecessary barrier instructions to

prevent an associated decrease in execution performance of the processing system. However, the conventional methods are not suitable for removing all of the unnecessary barrier instructions unless the user knows very well the way in which the parallel program will execute. Thus, a problem arises in that it is difficult to remove all of the unnecessary barrier instructions.

It is therefore an object of the present invention to provide a method of reducing unnecessary barrier instructions by which unnecessary barrier instructions are dynamically reduced without user (human) intervention, thereby enhancing the execution performance of the object code or module.

According to one aspect of the invention, unnecessary barrier instructions are reduced in a compiler for generating a parallel processing object program from a source program, wherein the compiler converts the source program into parallel processing objects (parallel processing execution divisions), which are units or blocks of code for parallel processing, and preferably issues immediately before a parallel processing execution division, a pre dynamic barrier instruction having information in parameters used for determining the necessity for a barrier. Further, preferably the compiler issues a post dynamic barrier instruction immediately before a reference position, which is a point in the source code or object code before each variable or array reference (or group of array references) to be referenced after a parallel processing loop

in the parallel processing execution division. The post dynamic barrier instruction has information in parameters thereof for determining the necessity for a barrier. Further, according to the invention, the parallel processing object program is preferably implemented by a hardware system for determining the presence or absence of data dependency, thereby dynamically reducing unnecessary barrier instructions based on the parameters of the pre dynamic barrier instruction and the post dynamic barrier instruction.

The above-mentioned object is also achieved by a compiler that generates, in converting the source program into the parallel processing object program or module, an instruction inserted before a parallel processing execution division having a parameter(s) with information used for determining the necessity for a barrier and an instruction inserted after the parallel processing execution division having a parameter(s) with information used for determining the necessity of a barrier before a variable or an array reference to be referenced after the parallel processing execution division. Further, the compiler determines the presence or absence of data dependency based on these parameters to dynamically switch between execution and nonexecution of a barrier instruction.

The above-mentioned object is also achieved, according to an embodiment of the invention, by a device that executes parallel processing of object code including dynamically

determining the necessity for a barrier operation by checking whether any of the following barrier instruction deletable conditions (1) through (3) are met by processing a parameter(s) with hardware, wherein a compiler generates a sequence of instructions to be used in making the determination or is provided with means for generating a code for switching between execution or nonexecution of a barrier instruction\_by a branch instruction that uses the barrier instruction deletable conditions (1) and (2) as a decision equation.

The barrier instruction deletable conditions are as follows:

- (1) Between PEs (Processor Elements), no dependency exists between a variable reference or an array reference to be referenced and a following reference;
- (2) Between PEs, a dependency exists between a variable reference or an array reference to be referenced and a following reference but this dependency is only within the same PEs and no dependency exists between different PEs; and
- (3) In hardware, memory coherence processing has been completed at a memory location at which a dependent relation occurs between PEs.

#### Brief Description of the Drawings

FIG. 1 is a diagram illustrating a schematic configuration of a pseudo FORTRAN language code and system for

describing a hardware-based method of reducing unnecessary barrier instructions according to a preferred embodiment of the invention:

- FIG. 2 is a block diagram illustrating an example of a configuration of a multiprocessor system to which the present invention is applied;
- FIG. 3 is a diagram illustrating an example of a source program having an inserted directive statement for reducing unnecessary barrier instructions;
- FIG. 4 is a diagram illustrating the way in which pre dynamic barrier instructions and post dynamic barrier instructions are executed on each PE;
- FIG. 5 is a flowchart of the operations followed in checking for the presence of a data dependency requiring a barrier by a dynamic barrier executing device and determining whether an instruction therefor has been completed; and
- FIG. 6 is a diagram illustrating a schematic configuration of pseudo FORTRAN language code and a system for describing a software-based method of reducing unnecessary barriers according to another preferred embodiment of the invention.

#### Detailed Description of the Preferred Embodiments

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The following describes a method of reducing unnecessary barrier instructions according to a preferred embodiment of

the invention with reference to Figs. 1-5.

FIG. 1 shows a schematic configuration of pseudo FORTRAN language code and a system used for performing a method of reducing unnecessary barrier instructions according to a preferred embodiment of the invention. FIG. 2 is a block diagram illustrating an example of the configuration of a multiprocessor to which the present invention is applied. In particular, FIGS. 1 and 2 show a source program 11, a compiler 12, a parallel processing object 13, such as an object program, module or section of object code, a program loader 14, a program storage medium 15, a multiprocessor system 21, a CPU 22, and a processor element (PE) 23.

As shown in FIG. 2, the multiprocessor system 21 to which the present invention is applied includes a program loader 25 for reading programs from a program storage medium 15, a CPU 22 for distributing the programs to processor elements (PEs) 23 that execute the programs. In operation, the multiprocessor system 21 receives parallel processing objects, which are preferably from the source program that have been put in form for parallel processing by the compiler 12, through the program storage medium 15 or directly from the compiler 12 at the program loader 25 and the CPU 23 distributes the parallel processing objects to the plural PEs 23, respectively. The compiler is a program stored as executable instructions on a storage medium or in memory 24. The PEs 23 are connected to memory 24 and operate in a shared

memory system according to the preferred embodiment, but each of the PEs could have its own memory and operate in a distributed memory system.

The following describes the method of reducing unnecessary barrier instructions practiced according to a preferred embodiment of the invention.

Referring to FIG. 1, the source program 11 has a DO loop 111 that is the same as a DO loop 31 in the prior art described with reference to FIG. 3. The compiler 12 transforms source program 11 into a plurality of parallel processing objects 13 (object code section or module, shown schematically in the figure for purposes of illustration). The parallel processing object, for example, 13 is a code section (parallel processing execution division) that includes a parallel processing loop for parallel-processing. The DO loop 111 of the source program 11 is to be parallel processed using the PEs 23 of the multiprocessor system shown in FIG. 2.

In transforming the DO loop 111 of the source program 11 into the parallel processing loop 132, a pre dynamic barrier instruction 131 and a post dynamic barrier instruction 133 are inserted to include parameters used to determine the presence or absence of a barrier, which is a determination to be made with hardware in the first embodiment or by software in the second embodiment. The pre dynamic barrier instruction 131 has parameters used for determining the necessity for a barrier of a variable or array reference to be referenced

inside the parallel processing loop 132. The barrier instruction 131 is issued immediately before the parallel processing loop 132. The post dynamic barrier instruction 133 has information in parameters relating to a variable or array reference (or group of array reference) to be referenced after the parallel processing loop 132. The post dynamic barrier instruction is issued immediately before a reference position, which is a point in the source code or object code occurring before each array reference or several array references. pre dynamic and post dynamic instructions specify, in the parameters, information of a base address (BA) 134, a stride width (SW) 135, an element length (EL) 136, and total number of elements (TN) 137 for the (first) variable or array reference in the parallel processing loop and the (second) variable or array reference to be referenced after the parallel processing loop, respectively as shown in Fig. 1.

The program based on the parallel processing object 13 generated by the compiler 12 as described above is stored in the program storage medium 15 by the program loader 14 to be passed to the multiprocessor system. The program storage medium 15 may be any of DAT, CMT, FD, CD-ROM, and MO, for example.

FIG. 4 illustrates the way in which pre dynamic barrier instructions and post dynamic barrier instructions are handled on each PE. FIG. 5 is a flowchart showing the processing followed in making the determination, with a dynamic barrier

executing device, whether there is a data dependency that requires a barrier and determining whether the execution of a memory access instruction for the data dependency has been completed.

First, referring to FIG. 4, the way in which the pre and post dynamic barrier instructions are handled on each PE (PE0 to PEn) will be described. Each of the PEs 23, upon execution of a pre dynamic barrier instruction 41, stores information including a base address  $(BA_{01}-BA_{n1})$  411, a stride width  $(SW_{01}-BA_{n1})$  $SW_{n1}$ ) 412, an element length ( $EL_{01}$ - $EL_{n1}$ ) 413, and total number of elements  $(TN_{01}-TN_{n1})$  414 for the variable or array reference to be referenced in the parallel processing loop 132, which are parameters or arguments, into each PE field of a communication register 42 which is connected to CPU 22. Also, a post dynamic barrier instruction 43 is issued with parameters having information including a base address (BA02-BAn2) 431, a stride width  $(SW_{02}-SW_{n2})$  432, an element length  $(EL_{02}-EL_{n2})$  433, and total number of elements  $(TN_{02}-TN_{n2})$  434 for a variable or array reference to be referenced after the parallel processing loop execution.

A hardware-based dynamic barrier executing device (DBED) 44, which is implemented in logic, not shown, that is part of the system 21 shown in FIG. 2, checks for a data dependency with respect to memory 24 to determine if a barrier is required. The determination is made by use of the parameters 431, 432 and 433 for each PE, respectively, specified in the

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post barrier instruction 43 and the corresponding information of parameters 411, 412 and 413 stored in the communication register 42 at execution of the pre dynamic barrier instruction 41. The DBED also determines whether a memory access instruction therefor has been completed (or memory coherence processing has been completed).

The following describes the above-mentioned decision processing to be performed by the DBED 44 (dynamic barrier executing device) with reference to FIG. 5.

- (1) First, the DBED checks for a data dependency that requires a barrier instruction. If no such data dependency is found, the DBED issues an NOP (No Operation) instruction (steps 51 and 512).
- (2) If a data dependency requiring a barrier instruction is found in step 51, then the DBED checks whether a memory access instruction in the parallel loop for the data dependency has been issued. If the memory access instruction has not been issued, the DBED issues a BARRIER (a barrier instruction) (steps 52 and 521).
- (3) If the memory access instruction is found issued in step 52, the DBED checks for the completion of that instruction (or the completion of coherence processing). If the execution of the memory access instruction is found completed, the DBED issues an NOP (steps 53 and 532).
- (4) If the execution of the memory access instruction is found to be not completed in step 53, indicating the need for

a barrier, the DBED issues an instruction for a barrier, a BARRIER (step 531).

In the above-mentioned processing flow, the processing in step 51 for checking for the data dependency that requires a barrier instruction is implemented by performing the following operation.

The base address, stride width, element length and total number of elements for a (first) variable or array reference is stored in the communication register 42 by a pre dynamic barrier instruction as  $BA_i$ ,  $SW_i$ ,  $EL_i$ , and  $TN_i$  for each  $PE_i(0 \le i \le max_{IPno}$ ,  $max_{IPno}$ : maximum PE number) and the base address, stride width, element length, and total number of elements for a (second) variable or array reference is stored in the communication register 42 by a post dynamic barrier instruction as  $BA_j$ ,  $SW_j$ ,  $EL_j$ , and  $TN_j$  for each  $PE_j(0 \le j \le max_{IPno}$ ,  $max_{IPno}$ : maximum PE number). Given these stored variables, if:

$$\begin{split} W_i &\cap R_j \neq \emptyset \text{ } \{0 \leq \exists_i \neq \exists_j \leq \text{max}_{\text{IPno}} \} \dots \text{ } (\text{relation 1}) \\ \text{for the set } W_i &= \{BA_i + SW_i * n_i , BA_i + SW_i * n_i + 1, BA_i + SW_i * n_i + 2, \dots, BA_i + SW_i * n_i + EL_i - 1 \mid 0 \leq n_i \leq TN_i - 1 \} \\ \text{and the set } R_j &= \{BA_j + SW_j * n_j , BA_j + SW_j * n_j + 1, BA_j + SW_j * n_j + 2, \dots, BA_j + SW_j * n_j + EL_j - 1 \mid 0 \leq n_j \leq TN_j - 1 \} \\ \text{then, the data dependency is found to be one that requires a barrier instruction. That is, if there is a memory dependency or overlap in a variable or array reference in the parallel$$

processing loop and a following variable or array reference, a barrier instruction is required.

FIG. 6 shows a schematic configuration of pseudo FORTRAN language code and a system for a software-based method of reducing unnecessary barriers according to another preferred embodiment of the invention. The following describes the above-mentioned processing of step 51 for checking for a data dependency that requires a barrier instruction. The example shown in FIG. 6 is generally the same as that shown in FIG. 1 except for the format of the source program 61 and the format of the parallel division loop 62, which is a parallel processing object to be converted.

To be more specific, as shown in FIG. 6, the abovementioned decision of the relation (1) can be performed by
transforming, with the compiler 12, the source program 61 into
the parallel processing object program (code section or
module) 62 to include a decision relation of an "if" statement
621, such as a conditional branch statement 621 having an
argument that, if satisfied, results in execution of the
branch instruction. Specifically, applying the abovementioned relation (1) to the statement 621 can generate a
branch instruction to be followed, which is in object code,
for switching between execution of a barrier instruction 622
and non-execution (following the branch) of the barrier
instruction 622. Then, the parallel processing object code
executing device can reduce unnecessary barrier instructions

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by executing this branch instruction for switching between execution and non-execution.

According to the above-mentioned second preferred embodiment of the invention, the following three barrier instruction deletable conditions are provided:

- (1) between PEs (Processor Elements), no dependency exists between a variable or array reference to be referenced and a following reference;
- (2) between PEs, dependency exists between a variable or array reference to be referenced and a following reference but this dependency is only within the same PE and no dependency exists between different PEs; and
- (3) in hardware, memory coherence processing has been completed at a memory location at which a dependent relation occurs between PEs.

Whether at least one of these conditions (1) through (3) is satisfied is determined by generating code for switching between execution and non-execution of a barrier instruction by a branch instruction having a decision relation, e.g. an "if" statement, based on the above-mentioned barrier instruction deletable conditions (1) and (2), thereby providing the dynamic determination whether a barrier operation is required or not. This allows the dynamic deletion of unnecessary barrier instructions under certain conditions by using a branch instruction to avoid execution of the barrier instruction, resulting in enhanced execution

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performance of a multiprocessor system.

As mentioned above and according to the invention, unnecessary barrier instructions in a parallel processing program having a dependency relationship known only at instruction execution can be dynamically deleted under certain conditions, resulting in the enhanced execution performance of a multiprocessor system.

While preferred embodiments have been set forth with specific details, further embodiments, modifications and variations are contemplated according to the broader aspects of the present invention, all as determined by the spirit and scope of the following claims.